Dr. David Reinkensmeyer Prof. John Stupar



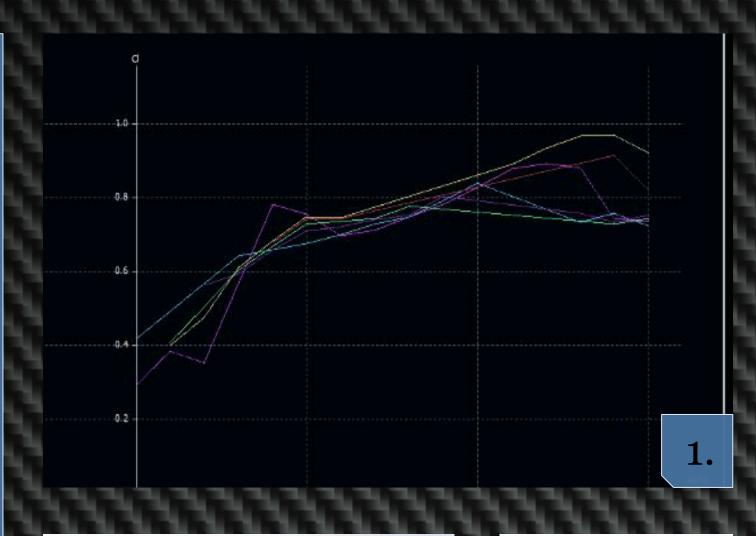
# U.S.R. Unmanned Search and Rescue

Team Leads:
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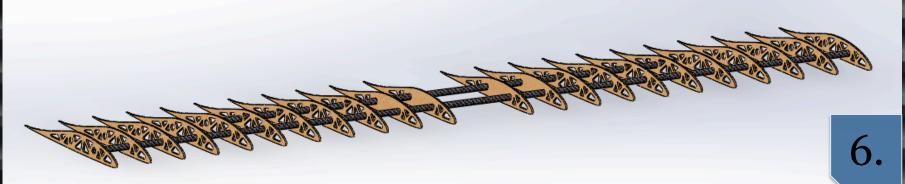
## Initial Design, Testing, and Analysis

- 1. CFD calculations for Klein-Fogleman stepped airfoil.
- 2. Control surface structure and wiring
- 3. Front landing gear
- 4. Rear landing gear
- 5. Laser-cut ribs for the wing
- 6. Wing design for full wingspan
- 7. Fuselage design and finite element analysis for balsa ribs
- 8. Aerodynamic drag calculations including skin friction

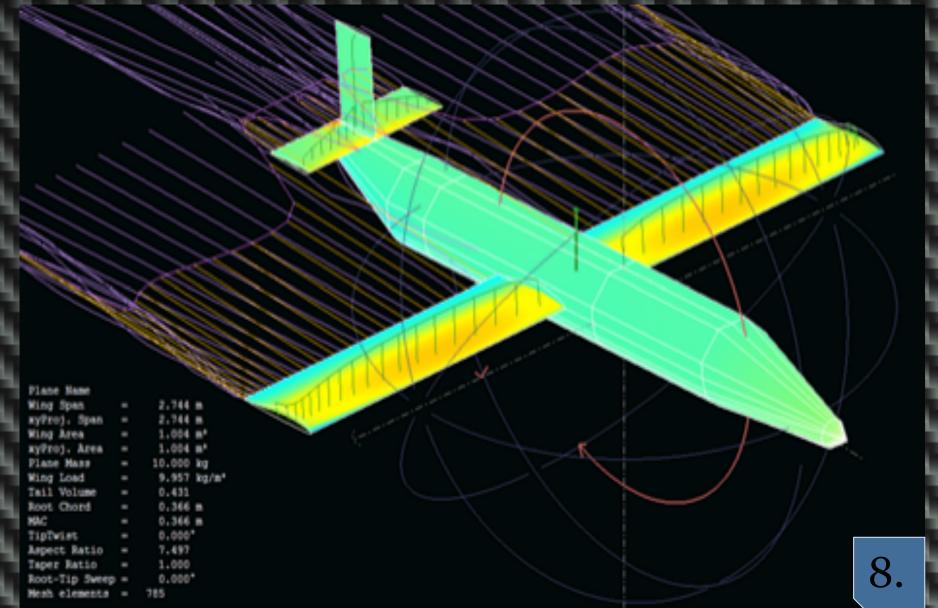












### Purpose:

To build an unmanned aerial vehicle for search and rescue capable of vertical takeoff and landing, plotting its own flight path based on user-inputted human attributes, and utilize solar energy to charge and recharge.

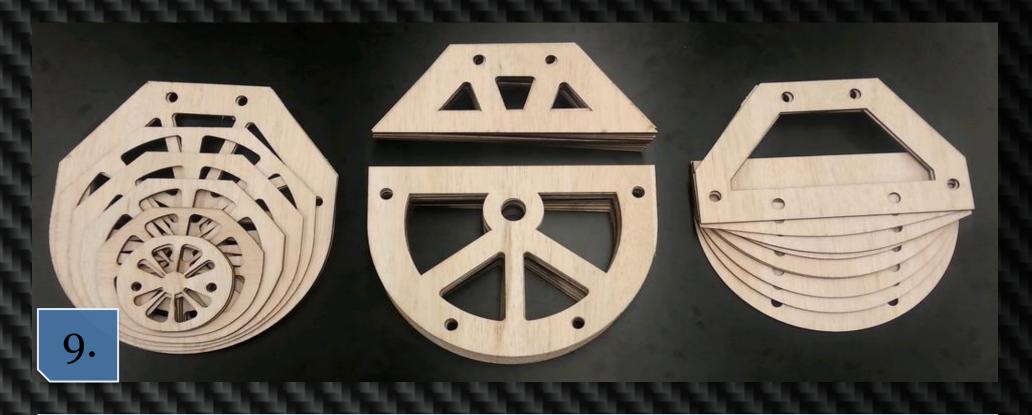
## **Spring Quarter:**

- Reorganized into specific teams with more clearly defined goals for greater utilization of time, energy, and resources
- Redesigned the plane for greater strength, durability, and actual flight
- Ran better simulations to gather more accurate data on every aspect of the plane
- Learned how to manufacture and utilized carbon fiber and other composites as a main method of fabrication
  - Fly!

### Team Structure:

- Wing Design
- Aerodynamics and V/STOL
- Fuselage Design
- Power Generation
- Propulsion and Landing Gear
- Programming and Controls
  - Manufacturing

# Manufacturing and Production



- 9. Balsa fuselage ribs after being laser cut
- 10. Custom solar panel built by Power Generation
- 11. First layer of carbon fiber going onto the fuselage
- 12. Fuselage "in work" in our lab in EG.
- 13. Wings and fuselage almost ready for assembly

